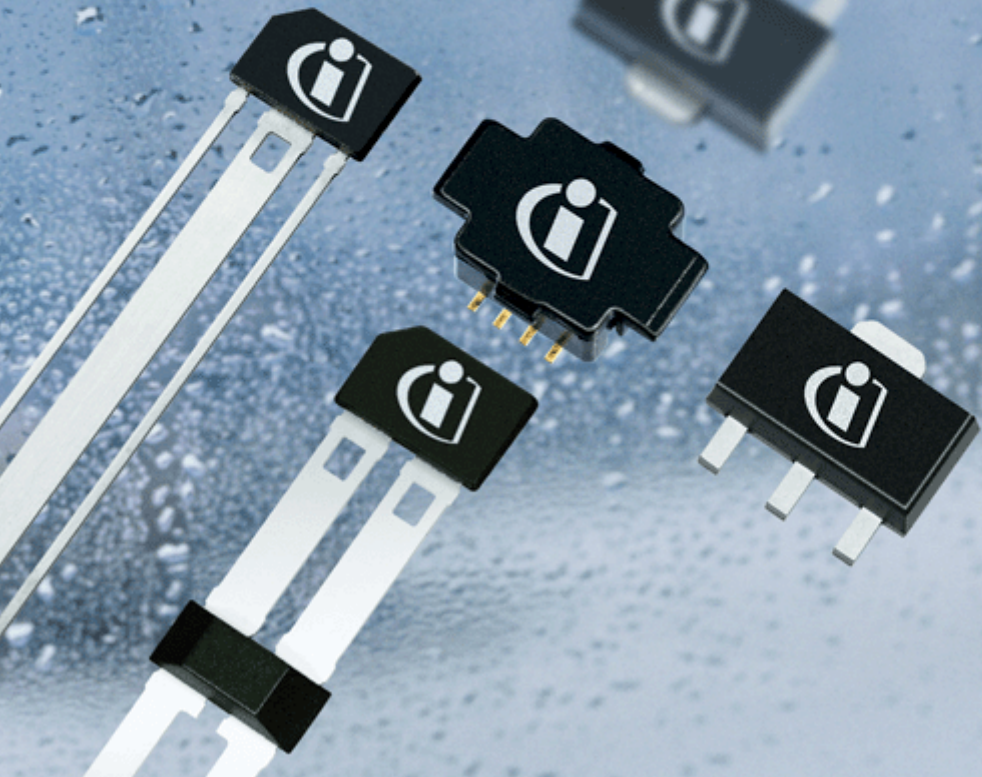


# TLE4976-1H TLE4976L

High Precision Hall-Effect Switch with  
Current Interface



Sensors



Never stop thinking

**Edition 2005-10**

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**TLE4976-1H**

**TLE4976L**

**Revision History:        2005-10**

V 1.1

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Previous Version:        1.0

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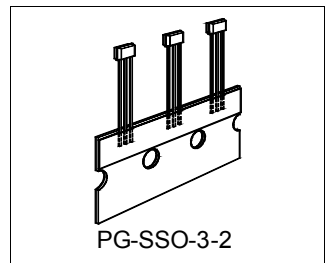
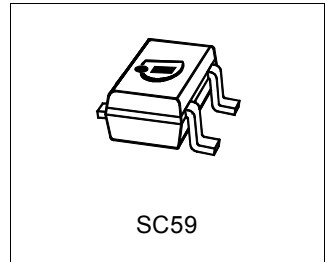
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## 1 Overview

### 1.1 Features

- 3.0 V to 26 V supply voltage operation
- High sensitivity and high stability of the magnetic switching points
- High resistance to mechanical stress by Active Error Compensation
- Reverse battery protection (– 18 V)
- Superior temperature stability
- Peak temperatures up to 195°C without damage
- Low jitter (typ. 1  $\mu$ s)
- High ESD performance ( $\pm$  8 kV HBM)
- Digital output signal with current modulation 6 / 14 mA
- Unipolar version
- SMD package SC59 (SOT23 compatible) - (TLE4976-1H))
- Leaded package PG-SSO-3-2 - (TLE4976L)



### 1.2 Functional Description

The TLE4976-1H and the TLE4976L are integrated circuit Hall-effect sensors designed specifically for highly accurate applications.

Precise magnetic switching points and high temperature stability are achieved by active compensation circuits and chopper techniques on chip.

Type	Package
TLE4976-1H	SC59
TLE4976L	PG-SSO-3-2

### 1.3 Pin Configuration (top view)

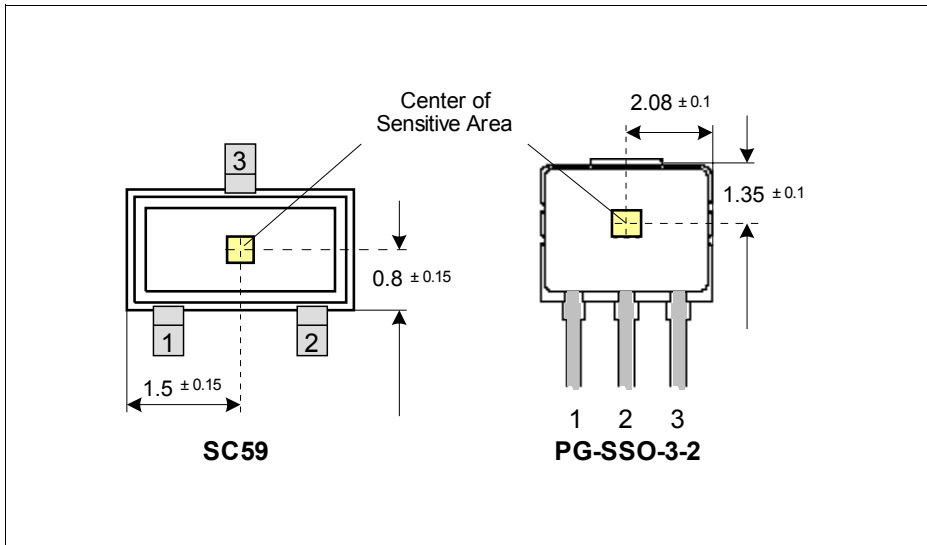


Figure 1 Pin Definition and Center of Sensitive Area

Table 1 Pin Definitions and Functions SC59

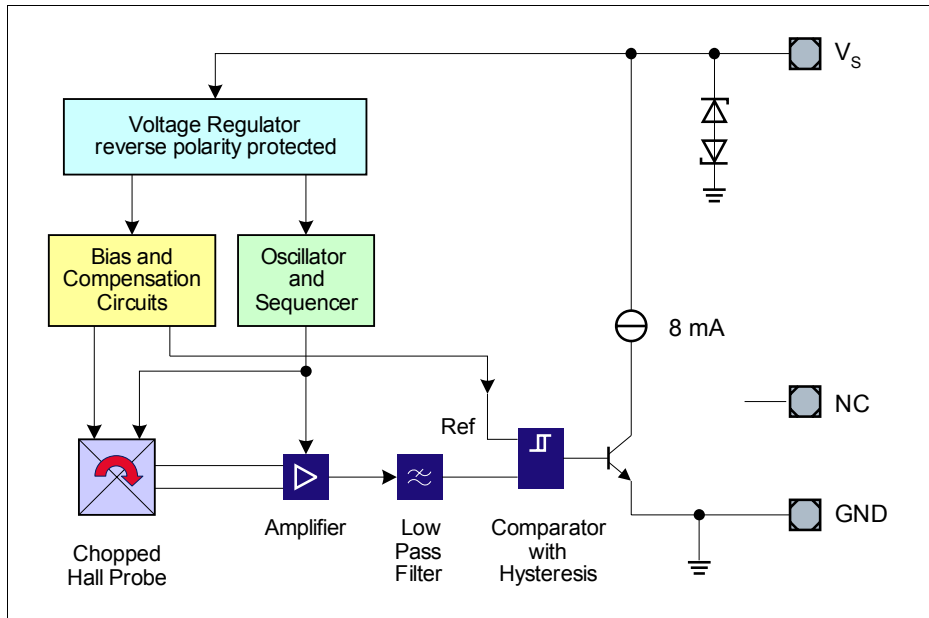
Pin No.	Symbol	Function
1	$V_S$	Supply voltage
2	N.C.	No internal connection
3	GND	Ground

Table 2 Pin Definitions and Functions PG-SSO-3-2

Pin No.	Symbol	Function
1	$V_S$	Supply voltage
2	GND	Ground
3	N.C.	No internal connection

## 2 General

### 2.1 Block Diagram



**Figure 2** Block Diagram

### 2.2 Circuit Description

The chopped Hall IC Switch comprises a Hall probe, bias generator, compensation circuits, oscillator, and output transistor.

The bias generator provides currents for the Hall probe and the active circuits. Compensation circuits stabilize the temperature behavior and reduce technology variations.

The Active Error Compensation rejects offsets in signal stages and the influence of mechanical stress to the Hall probe caused by molding and soldering processes and other thermal stresses in the package.

This chopper technique together with the threshold generator and the comparator ensure high accurate magnetic switching points.

The current consumption depends on the switching status.

### 3 Maximum Ratings

**Table 3 Absolute Maximum Ratings**
 $T_j = -40^{\circ}\text{C to } 150^{\circ}\text{C}$ 

Parameter	Symbol	Limit Values		Unit	Conditions
		min.	max.		
Supply voltage	$V_S$	- 18 - 18 - 18	18 24 26	V	for 1 h, $R_S + R_L \geq 75 \Omega$ for 5 min, $R_S + R_L \geq 75 \Omega$
Supply current through protection device	$I_S$	- 50	+ 50	mA	
Junction temperature	$T_j$	- - - -	155 165 175 195	$^{\circ}\text{C}$	for 2000 h (not additive) for 1000 h (not additive) for 168 h (not additive) for 3 x 1 h (additive)
Storage temperature	$T_S$	- 40	150	$^{\circ}\text{C}$	
Magnetic flux density	B	-	unlimited	mT	

*Note: Stresses above those listed here may cause permanent damage to the device. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.*

**Table 4 ESD Protection <sup>1)</sup>**

Parameter	Symbol	Limit Values		Unit	Notes
		min.	max.		
ESD voltage	$V_{\text{ESD}}$	-	$\pm 8$	kV	HBM, $R = 1.5 \text{ k}\Omega$ , $C = 100 \text{ pF}$ $T_A = 25^{\circ}\text{C}$

1) Human Body Model (HBM) tests according to: EOS/ESD Association Standard S5.1-1993 and Mil. Std. 883D method 3015.7



## 4 Operating Range

Table 5 Operating Range

Parameter	Symbol	Limit Values			Unit	Conditions
		min.	typ.	max.		
Supply voltage	$V_S$	3	–	18	V	for 5 min, $R_S+R_L > 100 \Omega$
		3		24		
Junction temperature	$T_j$	- 40	–	150	°C	for 168 h
		–	–	175		

## 5 Electrical and Magnetic Parameters

Table 6 Electrical Characteristics <sup>1)</sup>.

Parameter	Symbol	Limit Values			Unit	Conditions
		min.	typ.	max.		
Supply current low	$I_{SLOW}$	5	6	7	mA	$B > B_{RP}$ $V_S = 3\text{ V} \dots 18\text{ V}$
Supply current high	$I_{SHIGH}$	12	14	17	mA	$B < B_{OP}$ $V_S = 3\text{ V} \dots 18\text{ V}$
Reverse current	$I_{SR}$	0	–	0.2	mA	$V_S = -18\text{ V}$
Output fall time	$t_f$	–	0.4	1.6	$\mu\text{s}$	$R_S = 100\ \Omega$ , see: <b>Figure 3 “Timing Definition” on Page 12</b>
Output rise time	$t_r$	–	0.4	1.6	$\mu\text{s}$	
Chopper frequency	$f_{OSC}$	–	320	–	kHz	
Switching freq.	$f_{SW}$	0	–	15 <sup>2)</sup>	kHz	
Delay time <sup>3)</sup>	$t_d$	–	13	–	$\mu\text{s}$	
Output jitter <sup>4)</sup>	$t_{QJ}$	–	1	–	$\mu\text{s}_{RMS}$	Typical value for square wave signal 1 kHz
Power-on time <sup>5)</sup>	$t_{PON}$	–	13	–	$\mu\text{s}$	$V_S \geq 3.0\text{ V}$
Thermal resistance <sup>6)</sup>	$R_{thJA}$	–	100	–	K/W	SC59
		–	–	190		PG-SSO-3-2

1) over operating range, unless otherwise specified. Typical values correspond to  $V_S = 12\text{ V}$  and  $T_A = 25^\circ\text{C}$

2) To operate the sensor at the max. switching frequency, the value of the magnetic signal amplitude must be 1.4 times higher than for static fields.

This is due to the -3 dB corner frequency of the low pass filter in the signal path.

3) Systematic delay between magnetic threshold reached and output switching

4) Jitter is the unpredictable deviation of the output switching delay

5) Time from applying  $V_S \geq 2.7\text{ V}$  to the sensor until the output state is valid

6) Thermal resistance from junction to ambient

### Calculation of the ambient temperature (SC59 example)

e.g. for  $V_S = 12.0\text{ V}$ ,  $R_S = 100\ \Omega$ ,  $I_{SHIGHtyp} = 14\text{ mA}$  :

Power Dissipation:  $P_{DIS} = 148.4\text{ mW}$ .

In  $T_A = T_j - (R_{thJA} \times PDIS) = 175^\circ\text{C} - (100\text{ K/W} \times 0.15\text{ W})$

Resulting max. ambient temperature:  $T_A = 160^\circ\text{C}$

**Electrical and Magnetic Parameters**
**Table 7 Magnetic Characteristics TLE4976-1H and TLE4976L<sup>1)</sup>**

Parameter	Symbol	$T_j$ [°C]	Limit Values			Unit	Notes
			min.	typ.	max.		
Operate point	$B_{OP}$	- 40...150	5.5	9.25	11.0	mT	TLE4976-1H
		- 40	1.1	4.1	6.1		TLE4976L
		25	1.0	4.0	6.0		
Release point	$B_{RP}$	- 40...150	5.0	7.25	10.5	mT	TLE4976-1H
		- 40	3.1	6.1	8.2		TLE4976L
		25	3.0	6.0	8.0		
Hysteresis	$B_{HYS}$	- 40...150	0.5	2	3	mT	TLE4976-1H
		- 40	–	–	–		TLE4976L
		25	0.5	2.0	3.5		
Temperature compensation of magnetic thresholds	TC	–	–	0	–	ppm/°C	TLE4976-1H
				- 200			TLE4976L
Repeatability of magnetic thresholds <sup>2)</sup>	$B_{REP}$		–	40	–	$\mu T_{RMS}$	Typ. value for $\Delta B / \Delta t$ > 12 mT/ms

1) over operating range, unless otherwise specified. Typical values correspond to  $V_S = 12$  V.

2)  $B_{REP}$  is equivalent to the noise constant

*Note: Typical characteristics specify mean values expected over the production spread.*

**Field Direction Definition**

Positive magnetic fields related with south pole of magnet to the branded side of package.

## 6 Timing Diagram

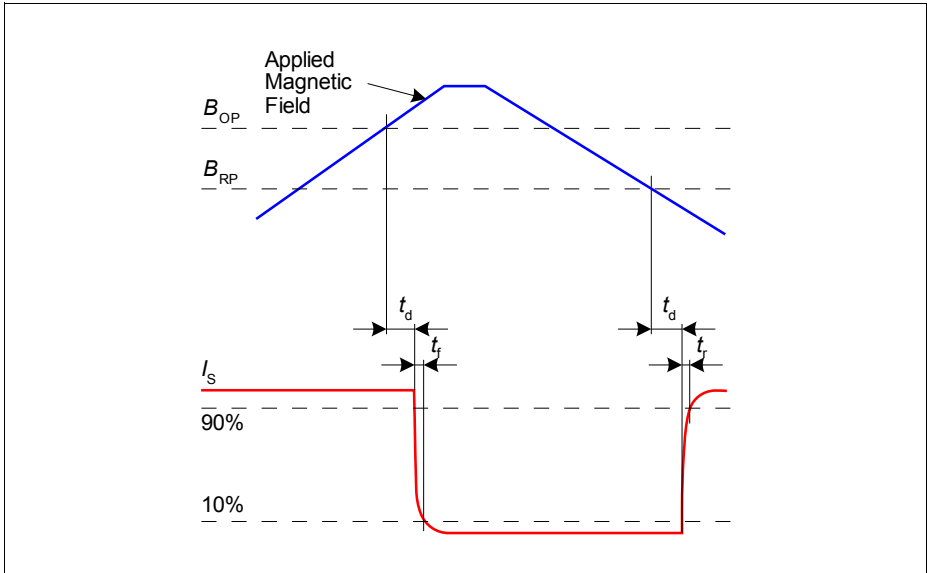


Figure 3 Timing Definition

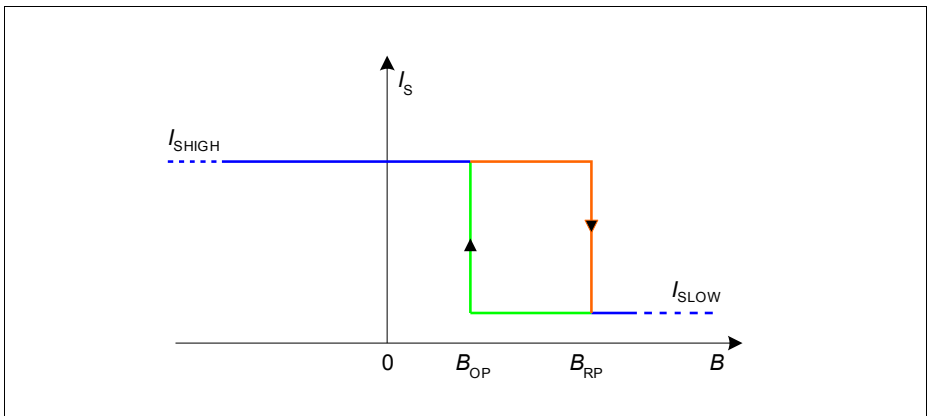


Figure 4 Output Signal

## 7 Application Circuit

The advantage of the current interface is, that only two wires are necessary to connect the sensor.

At least one series resistor is required to convert the two output states of the Hall sensor from current consumption to a voltage information.

A typical value for  $R_L$  is 100  $\Omega$ . This gives a typical signal voltage level  $V_{SIG}$  of 0.8 V in the Off state and 1.4 V in the On state.

If the sensor is operated in an application environment with disturbances on the supply line, an additional series resistor  $R_S$  is recommended. The maximum value for the series resistor  $R_S$  can be calculated using the following formula:

$$R_{Smax} = \frac{V_{Supplymin} - V_{Smin}}{I_{Shighmax}} - R_L$$

$V_{S,min}$  is the minimal supply voltage which might occur due to disturbances on the supply line  $V_S$ .

**Example:**  $V_{Supplymin} = 6 \text{ V}$ ;  $V_{Smin} = 3 \text{ V}$ ;  $R_L = 100 \text{ }\Omega$ ;  $I_{Shighmax} = 17 \text{ mA}$  :  $R_{Smax} = 76.5 \text{ }\Omega$

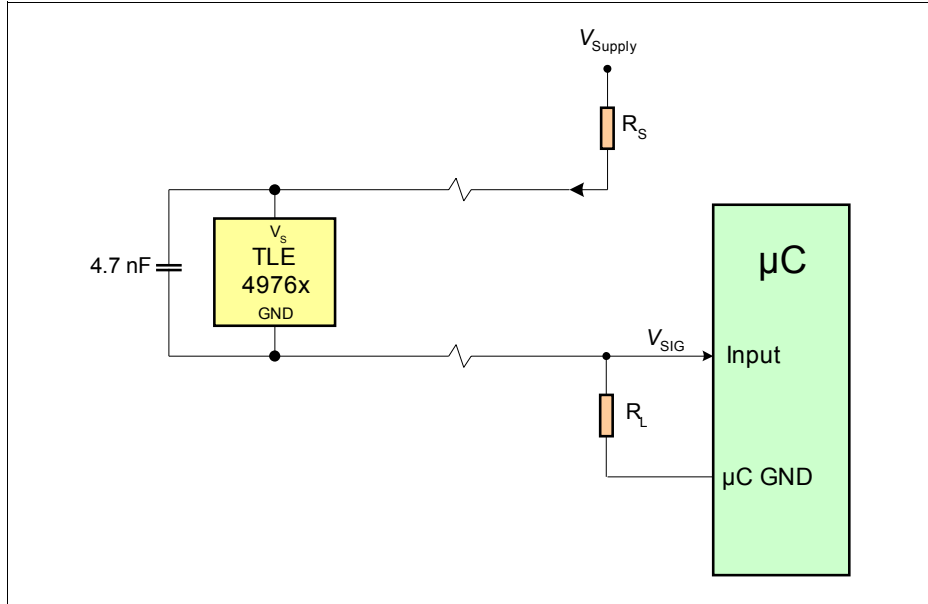


Figure 5 Application Circuitl

## 8 Package Information

### 8.1 Package Marking

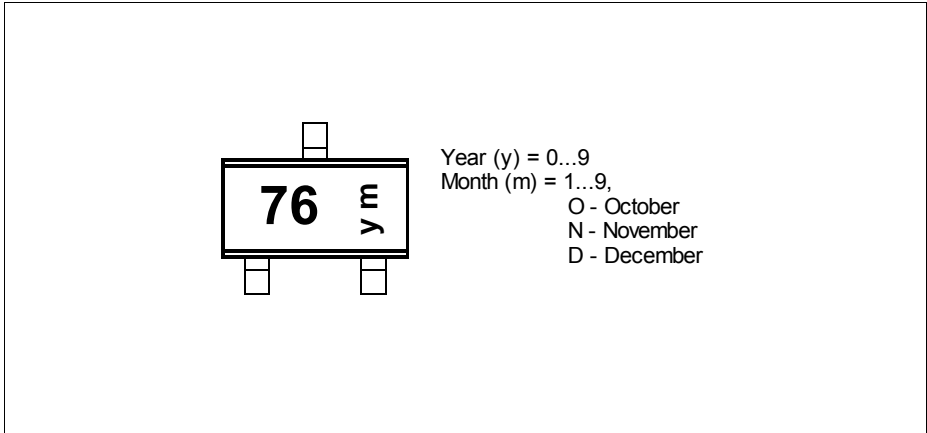


Figure 6 Marking TLE4976-1H

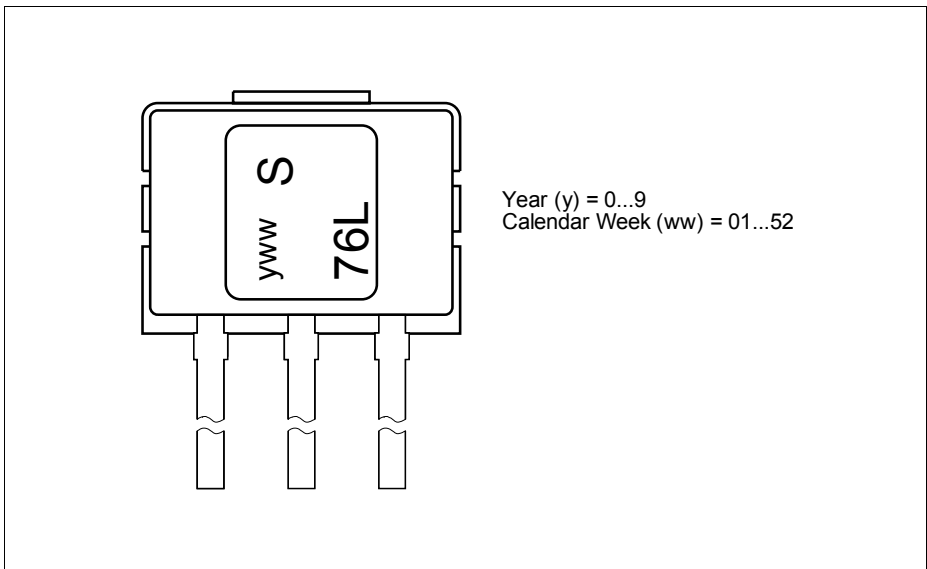
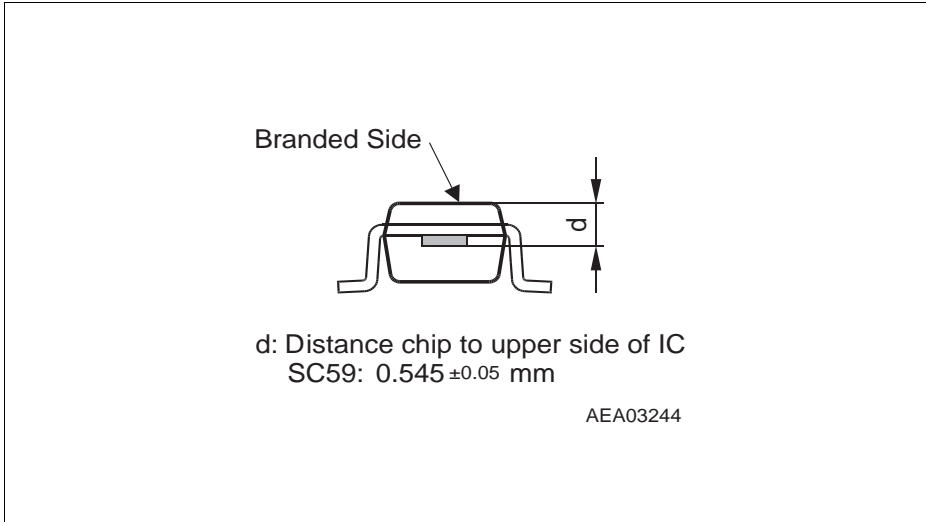
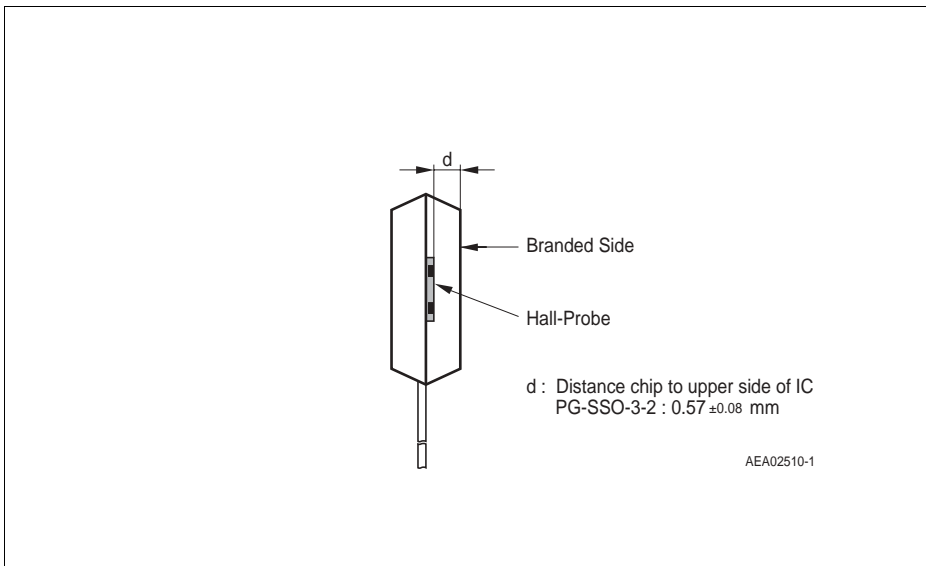


Figure 7 Marking TLE4976L

## 8.2 Distance between Chip and Package Surface



**Figure 8 Distance Chip SC59 to Upper Side of IC**



**Figure 9 Distance Chip PG-SSO-3-2 to Upper Side of IC**

### 8.3 Package Outlines

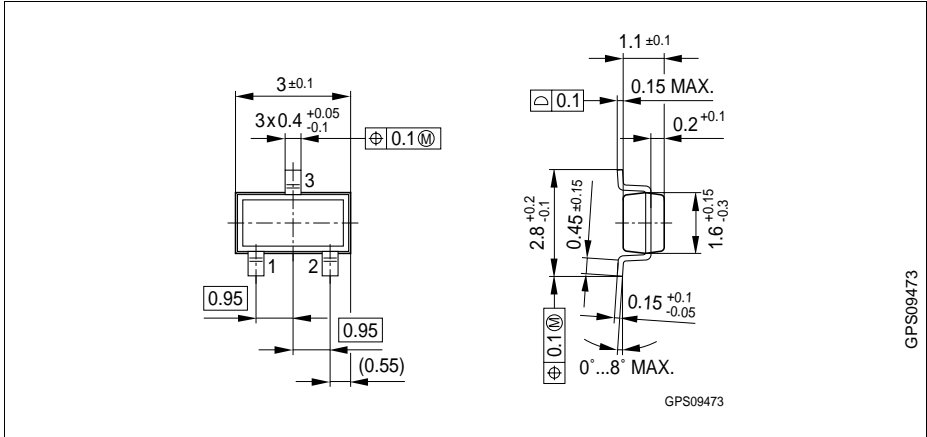


Figure 10 SC59

#### PCB Footprint for SC59

The following picture shows a recommendation for the PCB layout.

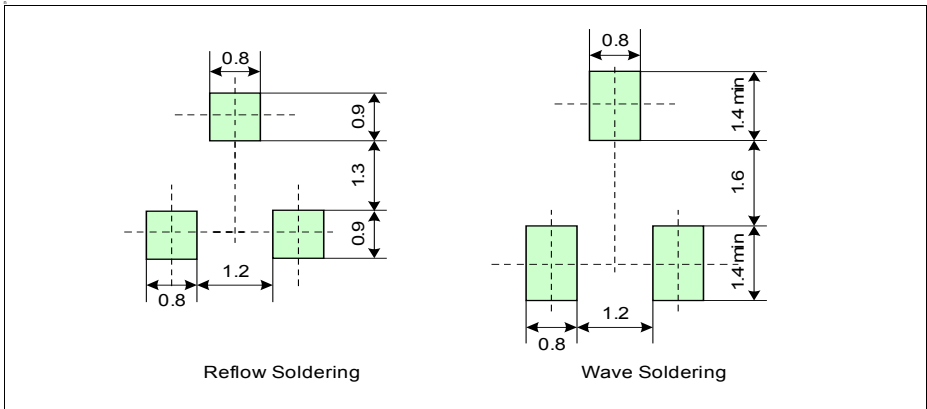


Figure 11 Footprint SC59 (SOT23 compatible)



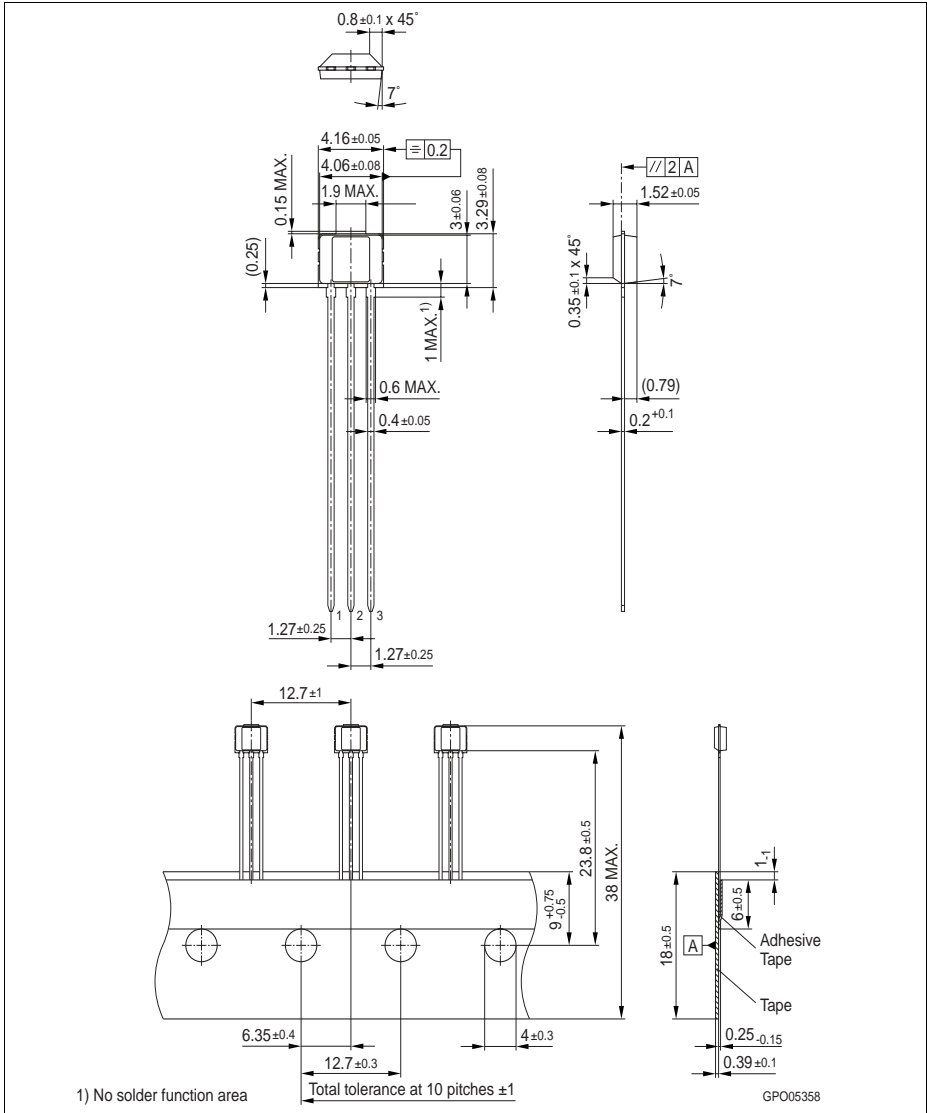


Figure 12 PG-SSO-3-2

Note: You can find all of our packages, sorts of packing and others in our Infineon Internet Page "Products": <http://www.infineon.com/products>.

Dimensions in mm





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